Choosing the Right Motors for your Mills

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Overview of Mill Selection

- Grinding testwork to characterise the project's oretypes
- Characterise hardness variability or load grinding results into block model
- Select mill sizes to achieve a desired throughput (or select a throughput based on desired mill sizes)
- Select motor(s) to fit the mills



Step 1: Mill overload power

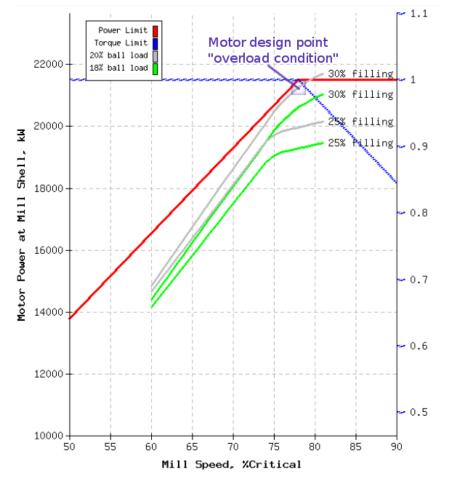
- Determine a set of operating conditions that reflects the maximum "overloaded" condition that the mill should be able to handle:
 - SAG mills: 20% v/v ball charge, 30% v/v filling and 78% critical speed with worn liners
 - Ball mills: 36% v/v filling and 78% critical speed with worn liners



Step 1: Mill overload power

- SAG mill, use a Tent Diagram to identify the design requirements
- Example, SG=4.0
 38'Ø × 19' EGL
 SAG
- Requires 21.5 MW at mill shell

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VII International Mineral Processing Seminar 8-10 December 2010. Sheraton Santiago Hotel & Convention Center, Chile Torque, per unit

Benchmarking Power Large Mill Power

■ 34' ● 36' ◆ 38' ★ 40' • 42+ First 42' mill 30 25 20% balls * *** Upgraded Pelambres mill 20 Upgraded * MM Freeport mill 15 First two 40' mills were underpowered 10 5 0 50 100 200 250 150 300 0 D^{2.5}×EGL 1000

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Step 2: Power measured where?

- The process conditions reflect power delivered to the mill shell
- The motor power reflects the motor output
- Motors with pinions and reducers must allow mechanical losses
 - makes the motor bigger to produce the same shell power



Step 3: Which Type?

- Three commonly used mill motor types:
 - Gearless drives

- largest size, up to 28 MW
- highest efficiency
- Synchronous with pinion
 - one or two pinion configuration, up to 15.6 MW
- Induction motor with speed reducer
 - one or two pinion configuration
 - cheapest capital, but poorest electric efficiency

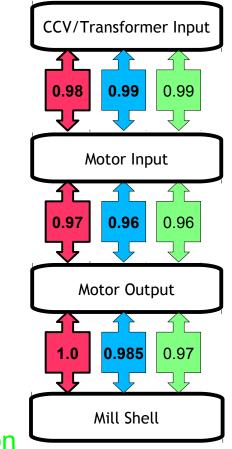


Step 3: Which Type?

- Electrical efficiency

 Gearless is highest
 Induction is lowest
- Directly affects operating costs
 - inefficient motors
 consume more
 power







Step 3: Which Type?

- Gearless is always variable-speed
- Synchronous and induction are normally fixed-speed
 - Can be made variable speed by adding more equipment and sacrificing electrical efficiency
 - In almost all cases, variable speed is costeffective for SAG mills
 - Variable speed for ball mills depends on the particular project and ore



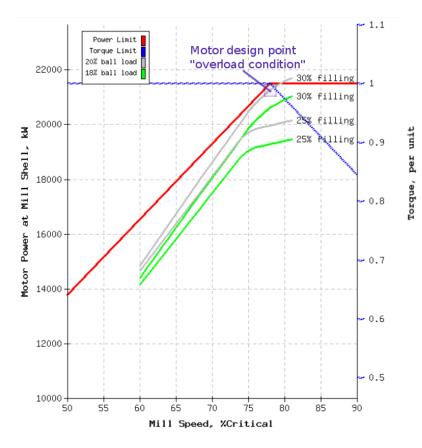
Step 4: Select Speed

- The rated speed of a motor is nominated by the engineer
- The torque output of a motor is constant up to the rated speed
- The power output of a motor is constant above the rates speed



Step 4: Select Speed

 Want the widest possible range of operating conditions



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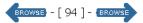
Case Study

- South American iron-ore project
- Variability in ore density
- 60,000 tonnes/day on 75% of samples
- Single line
 - 1 SAG, 38' Ø × 19' EGL
 - 2 ball mills, 22' Ø × 38' EGL

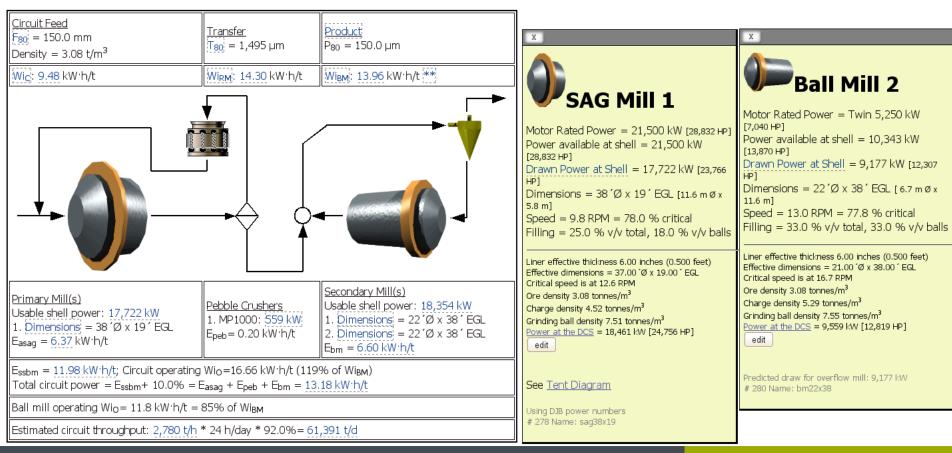


Case Study: Nominal operation

Case 03: one 38'x19' EGL SAG and two twin-pinion 22'x38' ball mills



DJB0092 Circuit 3



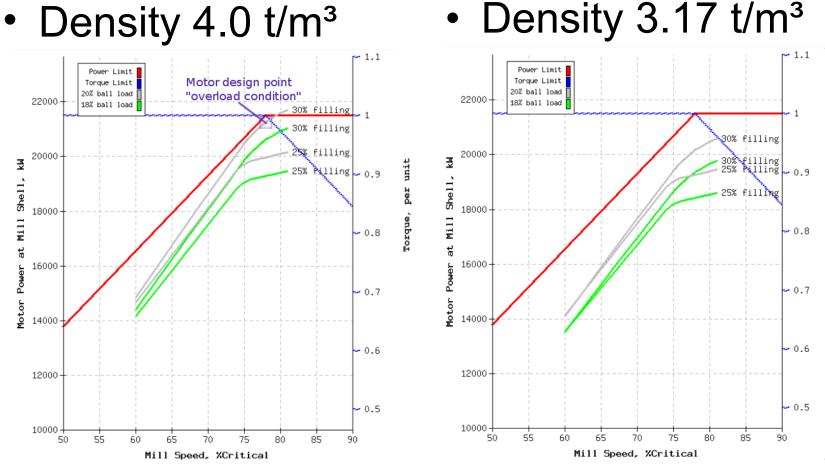
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Case Study, 21.5 MW SAG



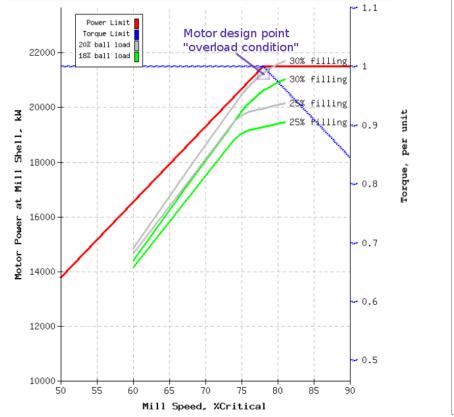
Torque, per unit

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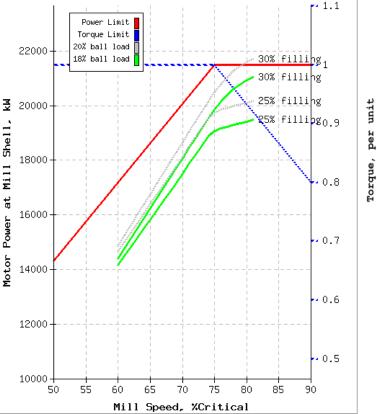
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Case Study, Design Speed

78% of critical



75% of critical



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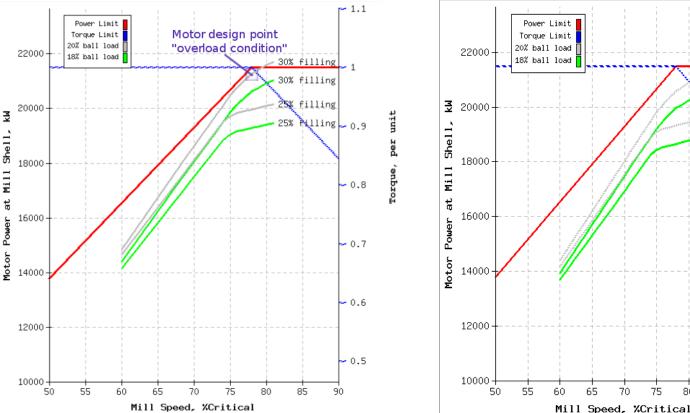
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Case Study, Liners

(based on change in mill volume, does not consider charge motion)

• New (150 mm)

• Worn (75 mm)



- 1.1

0.8

0.7

0.6

0.5

90

30% fillihg

30%¦fillihg

25% filling

25% fillibg0.9

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85

75

80

Conclusion

- Size grinding mills for nominal operating conditions (throughput targets)
- Size motors for "overload" conditions that may reasonably be encountered
 - High ball charge, volumetric filling
 - High density ore
 - Worn liners

